F.No. 63013/09/2014-Ord/BSF/MHA-Prov-1 1778 Bharat Sarkar/Government of India Griha Mantralaya/Ministry of Home Affairs PM Division

26, Man Singh Road, Jaisalmer House New Delhi, Dated 9th September, 2015

To,

DsG: AR (through LOAR), BSF, CISF, CRPF, ITBP, SSB, NSG & BPR&D.

Subject: QRs and Trial Directive for Under Vehicle Scanning System (UVSS) with Image & Automated License Plate Recognition System.

Sir,

The QRs and Trial Directives in respect of Under Vehicle Scanning System (UVSS) with Image & Automated License Plate Recognition System as per Appendix-A & B respectively have been accepted by the Competent Authority in MHA.

- 2. The CAPFs concerned will be accountable for correctness of the QRs/Trial Directives.
- 3. Henceforth, all the CAPFs should procure the above item required by them strictly as per the laid down Technical Specifications/QRs.

Yours faithfully,

Encl: As above

(Manohar N. Sukole)

Under Secretary to the Govt of India

Tel: 23381278

Copy forwarded to the Section Officer (IT), MHA with request to host the QRs and Trial Directives (soft copy being emailed separately) on the MHA website (under the page of Organizational Set up- Police Modernization Division-Qualitative Requirement under Surveillance Equipment.

(R.K. Soni)

Section Officer (Prov-I)

Copy to: DDG (Procurement), MHA.

Appendix-4

DIRECTOR GENERAL BORDER SECURITY FORCE (PROVISIONING DIRECTORATE (ORD SECTION)

The Sub-group of Technical Experts constituted by MHA vide their letter No. IV-24011/12/2011-Prov-I dated 13 Jun 2012, No. IV-24011/12/2011-Prov-I dated 28 Dec 2012 & UO No. IV-24011/12/2011-Prov-I- 350 dated 27 Jun 2013 held its meeting at BSF Headquarters on 21st November 2014, 23rd Jan 2015, 15th Apr 2015 and 12th May 2015 to formulate the Qualitative Requirement of 'Under Vehicle Scanning System (UVSS) with Driver Image & Automated License Plate Recognition System (ALPRS)'.

After detailed deliberations, the referred Sub-group has formulated the QRs of 'Under Vehicle Scanning System (UVSS) with Driver Image & Automated License Plate Recognition System (ALPRS)' which are as under:-

QUALITATIVE REQUIREMENTS OF UNDER VEHICLE SCANNING SYSTEM (UVSS) WITH DRIVER IMAGE & AUTOMATED LICENSE PLATE RECOGNIZION SYSTEM (UVSS) WITH

S.No A	
<u>A</u>	
	Specifications of UVSS:
1	The UVSS should be able to capture a very high resolution and complete
	composite under body image of any vehicle passing over it using a single high
 -	resolution area-3can Gige IP camera without requiring the vehicle to stop
2	The 0 v 35 should be able to handle vehicles moving at different area to
	from 0-40 km/ ir while the composite image captured by the system about 1.
	according to the speed of
_	Tushig multiple 100p-based sensors/IR Sensors
3	The composite imaging camera should be a high quality. Color Area Cons. C. E.
	1 9 PC/ With infilling AGA RESORTION OF 1074 Y 768 or above The minimum
	pecification of this area-scan camera shall he
	a) Camera type: Gigabit Ethernet Progressive Area-Scan Color Camera
	b) Sensor: 1/3 CCD
	c) Horizontal/Vertical Resolution 1024 x 768 Pixels or better.
	u) Frame rate: Minimum 50 fps at full resolution
	e) Camera Certification CE, FCC, with 30 FPS
1	f) Suitable Camera Casing.
ŧ	The UVSS should be capable of producing a clear and undistorted image of the
	vender 5 underside, even when a vehicle has completely stopped over the trace
	and nortest of the to the lease a seamless and nortest commonite in the
	tatteroide irrespective of the venicle stopping or moving in a non-uniform manner
	over the scamper.
	The UVSS must have a feature to magnify the composite images (current and
	First of the common to include a closer view of any part of the common to the inner in
	The underside indifficient must be adequate and obtained the state of
	and any long and LED lighting modules, it should not use Halogen on CEL to
	10-14118 Clements for infillithation of the inderende
	The UVSS should be able to dynamically and automatically adjust the brightness
	water contrast of the composite image so as to operate and a live.
	irrespective of the different external lighting conditions. The UVSS should also provide a feature to capture the image of the driver,
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5.No	Draft Qualitative Requirements
	captured through a suitable driver view camera.
9	The UVSS should give a real-time output of all the data simultaneously, i.e. the
	composite image, driver photos, vehicle front image and license Plate display (If
	Applicable) & all should be displayed on the monitor almost instantaneously.
10	The UVSS must have a built-in software diagnostics capability, to facilitate any
	distant software support to be offered offline.
11	The UVSS applications and operating software should be based on windows/
	Linux platform it must have a user friendly GUI with provision for multiple users
	logging of events and search facility.
12	The UVSS system must have a facility for backup of all transactions to any usual
	backup/storage media and also should be able to print out reports.
13	The UVSS underground camera should be enclosed in a suitable all-weather-proof
	housing of IP 67/66 equivalent or higher standard.
14	The Operating System should be Windows/ Linux.
15	The overall Installed unit should be properly designed, and its structure should be able to withstand a total vehicle 1.
	able to withstand a total vehicle load of up to 40 tons at any given point over the
	structure, more particularly at the center of the unit, so as not to suffer any
	accidental physical damage to the unit and components under the pit cover. A
	suitable pit Ventilation system should be provided to cool the UVSS during high
	temperatures. The installed unit should have automatic wiper system.
16	The front end of the software should be designed on Microsoft .NET/ Linux
	technology.
17	The back end database should be on latest version of SQL server.
18	The UVSS should have open protocol for integration with other security systems
	and also networking for any remote monitoring requirements.
9	The end of the day report should export the driver and the number plate image
	directly to a Microsoft excel sheet for future use or reference.
0	The UVSS should also provide a feature to capture the image of the driver for all
	RHS driven vehicles, captured through a suitable driver view camera.
1	The UVSS must have a feature to magnify the composite images (current and
	past), so as to facilitate a closer and zoom-up view of it.
2	Minimum Specifications of Driver Image Camera
	a) Sensor type shall be CCD/CMOS
	b) Pixel rate: 2MP
	c) Video format shall be NTSC/PAL
	d) Resolution shall be 520 TV lines or better.
	e) Power supply : 12 V DC
	Mechanical Structure : Structural Steel/
	Checqured with Rust Free Stainless Steel top
	Camera and light enclosure shall be Minimum
	IP 66 rated.
-	The Processing Unit should have:
	a) 8 GB RAM or better
	b) 2 TB HDD or better
0	Latest Intel Core i7 processor or better
C) Minimum 22" Display Monitor, Keyboard, Mouse
	2 25 platy Montol, Reyboard, Mouse

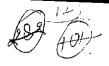
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S.No	Digit Qualitative Remiramanta
	e) Software for full functioning of the system
24	Sensor unit shall have Inductive loop sensor/ IR Sensors
25	Suitable Lighting Unit should be LED 220 V AC
26	Operating temperature: -10 °C to +55° C
27	IP 66 or better.
В	Specifications for Automated License Plate Recognition System(ALPRS):
1	The System should automatically detect a favorable International System (ALPRS):
	The System should automatically detect a four wheeler approaching the installed location by means of inductive loops.
2	On detection of vehicle approach the materials
	On detection of vehicle approach, the system would activate the license plate video capture cameras.
3	The system shall automatically detect the lines I
	The system shall automatically detect the license plate in the captured video feed in real-time.
4	
	The system shall perform OCR(Optical Character Recognition) of the license plate charters (English alpha-numeric characters in standard fonts).
5	The system shall store IDEC in a standard tonts).
	The system shall store JPEG image of vehicle and license plate and enter the
	license plate number into SQL Server or any other user specified database along with date timestamp and site location details.
6	System should be able to detect and an arrival to the state of the sta
	System should be able to detect and recognize the English alpha numeric License
	plate in all standard fonts and formats of all four wheelers including cars, HCV,
 7	
•	The system processing should be real time i.e. Instant the recognition of license number plates.
	
,	The system should be able to process and read number plates of vehicles with speed even up to 40 km/hr.
)	The system should store vides align (it is the system)
,	The system should store video clip of the vehicle approaching and leaving the location.
0	
	The system should have option to input certain license plates according to
	category like "Wanted", "Suspicious", "Stolen", "Expired". etc by authorized
	personnel. On successful recognition of the number plate, system should be able
	generate automatic alarm to alert the control room for vehicles which have been marked as "Wanted", "Suspicious", "Stolen", "Expired". System should have
	provision/expansion option to add more categories for future need.
1	System shall have onfine to be interested to the
	hardware/software on site.
2	The system shall enable easy and quick retrieval of snapshots, video and other
	data for post incident analysis and investigations.
3	The system should be able to generate suitable MIS reports that will provide
	meaningful data to concerned authorities and facilitate optimum utilization of
	resources. These reports shall include:
3.1	Report of vehicle flow at each of the installed locations for Last Day, last Week and
	Last Month.
3.2	Report of vehicles in the detected categories at each of the Installed locations for
	Last Day, Last Week and last Month.
	Report of Vehicle status change in different Vehicle Categories.

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14	The system	shall have option to save custom re	ports for subsequent use.
15	- 	shall have option to export report b	
		of the ALPRS or exporting into other	
16		should provide advanced and smar	
		atabase. There should be an option	
	i e	rith the specific number entered (up	2
17		should have option to add new cate	
18		should have option to update vel	
	authorized	personnel e.g. On retrieval of stole	en vehicle, system entry should be
	Changed from	om "Stolen" to "Retrieved".	
19	System sho	ould provide an option for adv	anced users to tune the system
	parameters.		
20	System sho	ould have option to configure site	e locations and data management
	settings.		_
21	The Centra	l Management Module shall run	on the ALPRS Central Server in
<u> </u>	control roor	n	
22	The system	should work in both day and night	conditions with good accuracy
23	The hardwa	re specification for the ALPRS shou	Id be a minimum of below:
	Camera	Interface	IP
		Format	HDTV 1080 or better
		Resolution	2 Megapixel or better
		Shutter Speed	1/50 to 1/10000 or better
		Operating	-10 °C to +55° C
:		Temperature(°C)	
		Frame Rate	25/30 FPS
	Lens	Vertical	5-50 mm
į		Electronic IRIS control	DC Type
]		Mount	C/CS
<u> </u>		Image Format	1/4" / 1/3" /1/2"
	IR	Wavelength	850 nm (Semi Covert)
	Illuminator	IR Illuminator Range	10-15 m
[Environment Protection	IP 65/IP 66
į	Filters	IR filter	
	Camera	Environment Protection Housing	IP 65/IP 66
	Housing		
	Processing	Processor	Latest Intel Core i7 processor
	Unit	RAM	8 GB
		Hard Disk Capacity	2 TB
-	Coood	Display Monitor	19" Flat
	Speed Limit		40 km/hr
	Installation		D. I. a. i.
i	and		Pole Mounted
1	Mounting		
	Integration	Canable of integration will it	11 12
	incgration	Capable of integration with the orand Access control System.	verall architecture of Surveillance
l_		and Access control System.	

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24.	Power Supply	The com to meet to be provide	the power requirement with	230 V AC ± 10 % suitable UPS backup of upto 1 hour should
	(B. C. Jos GINI B. Huluf (Henram		Roman or Day Allered (A-16. Shierely Accigi)	(Satisinder Lingh) Ac 17180 Lingh) (KAPIL, SSACEL, BPRED)
(F		H,SSB)	['] 5 H	(S.S.MANRITE, AC) SIW BSE

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DIRECTOR GENERAL
BORDER SECURITY FORCE

TRIAL DIRECTIVES OF UNDER VEHICLE SCANNING SYSTEM (UVSS) WITH DRIVER IMAGE & AUTOMATED LICENSE PLATE RECOGNITION SYSTEM (ALPRS)

S.No.	Onglitativa Danniwamanta	
Α	Specifications of UVSS	Draft Trial Directives
Irraenak	The UVSS should be able to capture a very high resolution and	Install the complete UVSS system with ALPRS and the ROO
	it using a single high resolution area-Scan Circ ID Compared with our	check the parameters accordingly.
	requiring the vehicle to stop.	
2	The UVSS should be able to handle vehicles moving at different	To be physically checked by the BOO by moving the sale.
	speeds ranging from 0-40 km/hr while the composite image	at different speed from 0-40 Km/hr.
	captured by the system should be automatically and dynamically	
	adjusted according to the speed of the vehicle using multiple loop-	
,	based sensors/IR Sensors.	
Ç	The composite imaging camera should be a high quality, Color	All parameters to be checked by the BOO through the
	Area Scan, GigE type, with minimum XGA resolution of	literature of the product and images should be checked at the
	camera shall be:	given resolution accordingly.
	a) Camera type: Gigabit Ethernet Progressive Area-Scan Color	For parameter (e), Supplier will submit CE, FCC, 30 FPS
	Camera.	certification for camera.
	b) Sensor: 1/3" CCD	
	c) Horizontal/Vertical Resolution 1024 x 768 Pixels or better.	Camera casing will be checked physically at the time of trial.
	d) Frame rate: Minimum 50 fps at full resolution.	
	e) Camera Certification CE, FCC, 30 FPS	
	t) Suitable Camera Casing.	
4	The UVSS should be capable of producing a clear and undistorted	To be physically checked by the BOO by scanning the
		underbelly of vehicle in both moving and still condition
		S mer convention
	create a seamless and perfect composite image of the underside	
	rrespective of the vehicle stopping or moving in a non-uniform	
	manner over the scanner.	
<u>ر</u> ن 	The UVSS must have a feature to magnify the composite images	Both current image and recorded image Image distantion
_	order to facilitate a closer view of any part of	While zooming in etc would also be checked by the ROO
<i>\</i>		





through any state-oche-art, long-life LED lighting medules. It should not use Halogen or CEL-pp lighting medules. It should not use Halogen or CEL-pp lighting medules. It should not use Halogen or CEL-pp lighting medules. It should not use Halogen or CEL-pp lighting elements for the LVSS should be an experient of the composite image, so as to ensure do quight, mages, irrespective of the different external lighting conditions. The LVSS should be be to Apramically and automatically adjust in the LVSS should be been of the different external lighting conditions. The LVSS should be provide a feature to capture the image of a fill the data is minuteneously, i.e. the composite image, driver photos, vehicle front image and license Hase desipale (if Applicable) & all the data is minuteneously, i.e. the composite image, driver photos, vehicle front image and license Hase desipale (if Applicable) & all should be displayed on the monitor almost instantaneously, i.e. the composite image driver photos, vehicle front image and license Hase desipale (if Applicable) & all should be displayed on the monitor almost instantaneously. In LVSS should give a real-time output of all the data is an extended of the control of the unit of an antible line of the monitor almost instantaneously. In the LVSS should give a real-time output of all the data is a light of the ligh	0	Qualitative Requirements	Draft Trial Directives
	um of- Hal	mination must be adequate and obtained f-the-art, long-life LED lighting modules. It alogen or CFL-type lighting elements for nderside.	To be physically checked by the BOO.
	con	able to dynamically and automatically adjust ontrast of the composite image, so as to ensure irrespective of the different external lighting	To be physically checked by the BOO in both low light and daylight.
	alsc 1 th	so provide a feature to capture the image of hrough a suitable driver view camera.	
	f g	give a real-time output of all the data the composite image, driver photos, vehicle ase Plate display (If Applicable) & all should nonitor almost instantaneously.	To be physically checked by the BOO
	ve. it sc	a built-in software diagnostics capability, to software support to be offered offline.	Supplier should submit the software in CD-R or any standard portable storage media which should support any distant software in offline mode.
	ions Jatt ple	ns and operating software should be based on thorm it must have a user friendly GUI with a users logging of events and search facility.	To be physically checked by the BOO
	n ı / us : rep	must have a facility for backup of all isual backup/storage media and also should ports.	To be physically checked by the BOO
	rom	 .	NABL accredited lab certificate to be provided by the bidder.
	tem	n should be Windows/ Linux.	To be physically checked by the BOO.
	ed ab n p n p nit, nit ation ten	unit should be. properly designed, and its ble to withstand a total vehicle load of up to point over the structure, more particularly at t, so as not to suffer any accidental physical and components under the pit cover. A on system should be provided to cool the emperatures. The installed unit should have sm.	To be physically checked by the BOO and the bidder will provide OEM certificate.

To be physically checked by the BOO.
To be physically checked by the BOO and the bidder will provide OEM certificate
To be physically checked by the BOO along with technical literature of the camera.
To be physically checked by the BOO along with technical literature of the camera.
To be physically checked by the BOO.
To be physically checked by the BOO and the bidder/supplier will provide OEM certificate.
To be physically checked by the BOO.
To be physically checked by the BOO and the bidder/supplier will provide OEM certificate.
Draft Trial Direc To be physically checked by the BOO

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S.No.	Qualitative Requirements	Draft Trial Directives	The state of the s
26	Operating temperature: -10 °C to +55° C	NABL accredited lab certificate to be provided by the hidder	No.
	IP 66 or better.	NABL accredited lab certificate to be provided by the hidder	
	Specifications for Automated Number Plate Recognition System(ALPRS):		
	hould automatically detect a four	To be abusinally about all 12, the DOO	
	oaching the installed location by means of indu	to be physically effected by the BOO	
	On detection of vehicle approach, the system would activate the	To be physically checked by the BOO	
	captured video feed in real-time.	To be physically checked by the BOO	
	The system shall perform OCR(Optical Character Recognition) of	To be physically checked by the BOO	
	the license plate charters (English alpha-numeric characters in standard fonts).		
	The system shall store IPEG image of vehicle and license plate and	To be physically checked by the BOO	
	enter the license plate number into SQL Server or any other user		
	specified database along with date timestamp and site location		
	details.		
	System should be able to detect and recognize the English alpha	To be physically checked by the BOO	
	numeric License plate in all standard fonts and formats of all four		
	wheelers including cars, HCV, LCV.		
	The system processing should be real time i.e. Instant the	To be physically checked by the BOO	
	recognition of license number plates.		÷
	The system should be able to process and read number plates of	To be physically checked by the BOO	
	vehicles with speed even up to 40 km/hr.		
	The system should store video clip of the vehicle approaching and leaving the location	To be physically checked by the BOO	
	The system should have option to input certain license plates	To be physically checked by the BOO	
	according to category like "Wanted", "Suspicious", "Stolen",	to be proposed by the DOO	
	"Expired". etc by authorized personnel. On successful recognition		
	of the number plate, system should be able generate automatic		
	alarm to alert the control room for vehicles which have been		
	should have provision/expansion option to add more categories for future need		
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0:10	Quantauve Kequirements	Draft Trial Directives
Ξ	System shall have option to be integrated with other access control hardware/software on site.	To be physically checked by the BOO and the bidder/supplier will provide OFM certificate
12	The system shall enable easy and quick retrieval of snapshots, video and other data for nost incident analysis and incident.	To be physically checked by the BOO
13	system should be able to ge	
	will provide meaningful data to concerned authorities and facilitate optimum utilization of resources. These reports shall include:	
13.1	Report of vehicle flow at each of the installed locations for Last	To be physically checked by the BOO
	Day, last Week and Last Month.	
13.2	Report of vehicles in the detected categories at each of the Installed locations for Last Day, Last Week and last Month	To be physically checked by the BOO
13.3	Report of Vehicle status change in different Vehicle Categories.	To be physically checked by the ROO
4	The system shall have option to save custom reports for subsequent use.	To be physically checked by the BOO
15	The system shall have option to export report being viewed to common format for use outside of the ALPRS or exporting into other systems.	To be physically checked by the BOO.
16	ould provide advanced and smart searching facility es from the database. There should be an option of	To be physically checked by the BOO
	searching number plates almost matching with the specific number entered (up to 1 and 2 character distance).	
17	The system should have option to add new category by authorized personnel.	To be physically checked by the BOO
18	ve option to update vehicle status in specific zed personnel e.g. On retrieval of stolen	To be physically checked by the BOO
	Changed from "Stol	
19	System should provide an option for advanced users to tune the	To be physically checked by the BOO and the bidder/supplier
20	System should have option to configure site locations and data	To be physically checked by the BOO by login as
21	The Central Management Modifie shall with on the AI DRS Control	administrator only.
	Cuitini	To be brighten by checken by alle DOO

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Server in control room. The system should work in both day and night conditions with good accuracy. The hardware specification for the ALPRS should be a minimum of below: Camera Interface IP HDTV 1080 or better Resolution 2 Megapixel or better Resolution 2 Megapixel or better Resolution 2 Megapixel or better Shutter Speed 1/50 to 1/10000 or better Coperating 1/50 to 1/1000 or better Shutter Speed 1/50 to 1/1000 or better Coperating 1/50 to 1/1000 or bette	Draft Trial Directives	and night conditions with To be physically checked by the BOO by checking in daylight and dark hours.	be a minimum		tter	tter	r better								To be physically checked by the BOO along with technical									processor						
cy should work in bo cy re specification for Interface Format Resolution Shutter Speed Operating Temperature(°C) Frame Rate Vertical Mount Image Format Wavelength IR Illuminator Range Environment Protection IR filter	Kequirements	th day and night c	the ALPRS should	IP	HDTV 1080 or better	2 Megapixel or bet	1/50 to 1/10000 or	-10 °C to +55° C		25/30 fps	5-50 mm	DC Type		C/CS	/ 1/3"/	850 nm (Semi Cove	10-15 m		IP 65/IP 66		778781	1P65/IP66	1 04000 Total 6 10 10	8 GB	2 TB		19" Flat	40 km/hr	Pole Mounted	
	trol room.	should work in bo	re specification for	Interface	Format	Resolution	Shutter Speed	Operating	Temperature(°C)	Frame Rate		nic	control	Mount	Image Format	Wavelength	IR Illuminator	Range	Environment	Protection	IR filter	Environment	Proceedion Housing	RAM		Capacity	Display Monitor			

					_			
	-	124	2			_		7
	Supply	Power	٦ 		G	Integration		
backup of upto 1 hour should be provided	% suitable UPS to meet the power requirement with	The complete system shall operate on 230 V AC \pm 10 To be physically checked by the BOO.	, , , , , , , , , , , , , , , , , , ,	Surveillance and Access control System	Superior of most anon with the overall architecture of 10 be phys	Canable of integration with the	Quantative Requirements	
		To be physically checked by the BOO.	will provide Obly certificate.		To be physically checked by the BOO and the hidder/sunnlier	CAAIDAHAT INTEL 180 LA	Draft Trial Dimostives	
				Serio Portor	unnlier			-
		L			نـــ		23	4

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DIRECTOR GENERAL
BORDER SECURITY FORCE