GOVERNMENT OF INDIA

(Ministry of Home Affairs)

Communication & IT Directorate CENTRAL RESERVE POLICE FORCE

EAST BLOCK-7, SEC-1, R.K. PURAM, NEW DELHI-110066

(Tele/Fax No-011-26107493, Email-Id: comncell@crpf.gov.in)

No. B.V-7-C/2024-25-C(N/UAV)-Q

Dated, the

April'2025

Subject: - REQUEST FOR COMMENTS OF STAKEHOLDERS /OEM/FIRMS on Draft QRs & TDs of "Nano UAV".

- 1. The Draft QRs/TDs of "Nano UAV" is attached as **Appendix 'A'**. The OEMs/Vendors are requested to forward information of the product, which they can offer and also forward correct specifications of their system against each parameter. Only complied or not complied remarks will not be accepted. The firms are also requested to furnish the following details:-
 - Whether you are OEM/Vendor?
 - If vendor details of OEM.
 - Authorization certificate from OEM.
 - 2. The required information/details may please be forwarded at the following addresses by _____ May'2025.

Communication Directorate, CRPF

East Block-7, Sec-1, R.K. Puram, New Delhi-110066

Email: comncell@crpf.gov.in

3. An early response is requested.

(Amit Taneja)

DIG (Equipment)

Communication & IT Branch Directorate General, C R P F

Draft QRs/TDs of Nano UAV

SN	Parameter	Draft QRs/TDs of Nano UAV Specifications	Trial directives
1		(As per drone rule 2021) sys	
1		(As per drone rule 2021) sy: lb-systems: -	stem should consist of the
1.1		th battery pack	Board will check it practically
1.2		ontrol station with data link	and will ensure that items
	equipment		are available as per tender
1.3		night Camera Payload	publication.
1.4		attery Charger with Power Supply	
2	System	haracteristics:-	
2.1	Role	Personal soldier Surveillance,	Board will check it practically
4.1	Roic	air platform of very small size of	during day and night and will
		close range surveillance and	ensure that UAV equipped
		detection during day and night.	with these features.
2.2	Launch	i) Vertical Take Off and Landing	Board will check practically
	and	(VTOL) or	by within the shown area
	Recovery mode (In	Hand Launch and Belly landing	and will ensure that payload
	mode (In meter)	within an area of 2m x 2m	should not get damaged during recovery of UAV.
	,	clearing or less	
2.3	Aural	≤40dBs at 40 feet Above Ground	
	Signature	Level	certificate of Govt. Lab. or
	(in dB)		DRDO or NABL accredited or ILAC accredited laboratory.
2.4	Payloads	Should have capability to carry	Ü
	carrying	electro Optic (EO) for day and	Board will effects practically.
	capability	Thermal Imager (TI) for night	
		one at a time.	
		Or	
		Integrated day & Night payload.	
		(As per user requirement)	
2.5	Flight	a) Semi autonomous vertical	Board will check practically.
	Modes	take off or hand launch.	_
		b) Semi autonomous vertical	
		landing or belly landing.	
		c)Hover at defined waypoint	
		d) Semi Autonomous waypoint	
		navigation (pre-defined as well as dynamically adjustable	
		waypoints during flight)	
		e) Remote Piloted mode for	
		video based user navigation.	
		f) Vision based Semi	
		Autonomous Target Tracking of	
		fixed and moving targets.	
		g) Should be controllable in real time from the GCS up to	
		recovery.	
		h) Fully autonomous in outdoor	
		environment.	
2.6	Endurance	20 minutes or more with all	Board will check practically
	(In	payloads at Mean Sea Level.	with maximum payload up to
	minutes)		launch altitude of 1000 meter Above Mean Sea Level
			(AMSL).
	l		()·

SN	Parameter	Specifications	Trial directives
2.7	Operating	100 feet AGL (Above	Board will check practically by
	Altitude (In feets)	Ground Level) or more.	flying the UAV.
2.8	Launch	2000m AMSL (Above	Firm will submit OEM
2.0	Altitude (in	Mean Sea Level) or more	certificate.
	meter)	Mean oca bever, or more	
2.9	Range of	Minimum 1.5 km line of	Board will check practically.
	Operation (In	sight	
	Km)		
2.10	Cruise Speed	20 km/h or more	Board will check practically
	(In km/h)		and firm will submit OEM certificate.
2.11	Operating Wind	a) Take off: 10 knots or	Board will check it practically
	Conditions (In	more	or firm certificate will be
	knots)	b) Landing: 10 knots or	accepted in this regard.
		more	
		c) gust: 15 knots or more	
2.12	Fail safe	a) Automatic Return to	Board will check it
	features	Home/ Land on low battery	practically.
		b) Single GPS on-board	Firm will submit OEM certificate.
2.13	Propulsion	Electrical with	Board will check it practically.
	system	rechargeable batteries	
3.	Payload charact	eristics:-	
3.1	Payloads required	a) Electro Optic (EO) for day (colour) b) Thermal Imager (TI) or IR for night c) Integrated day & night payload.	Board will check practically after fitting the required payloads and ensure that UAV working satisfactorily.
		(As per user requirement)	
3.2	Payload and	a) Video output should	Board will check practically all
	Video	be digitally stabilized at all zoom levels.	parameters
	Stabilization	b) Quality of video	
		should not be affected by	
		UAV vibrations.	
3.3	Electro optic	a) Resolution: 1280 X	Board will check it practically
	(EO) Daylight	720 pixel or better	and ensure daylight payload working as per their
	Payload		parameters and firm will submit OEM certificate for resolution and FOV.

SN	Parameter	Specifications	Trial directives
		b) Should be able to detect human	
		size target at 100-meter slant or more	
3.4	Thermal Imager (TI)	a) Resolution: 320 X 240 pixels or better	Board will check it practically and ensure
	Imager (TI) Night or IR	b) White/Black Hot modes for TI	daylight payload working
	Payload (As per user	payload	as per their parameters and firm will submit
	(As per user requirement)	ej Bigitai 200m. 12 or more	OEM certificate for
	,	d) Should be able to detect human size target at 70-meter slant or more	resolution.
3.5	Night Recovery	Switchable (from GCS) LED light	Board will check it
1	Beacon	when operating with Night Payload	practically.
4.		Station characteristics:-	Board will check it
4.1	inch tablet	edized 7- Compatible with Nano UAV	Board will check it practically.
	Or	·	
	As per user requ	irement.	
4.2		dware only for option (a)	
	CPU	Processor minimum frequency 2.9	BOO will check it
	Q4	GHz or equivalent /better	practically one by one all
	Storage	256 GB or better 4 GB or more	parameter, and supplier will also provide OEM
	Memory Display	Minimum 8 inch – 1024 x 768 XGA	certificate in this
	Display	sunlight readable screen, anti-glare.	regards. Ensure all
		7 0	parameters are available in the equipment.
4.3	Battery	Minimum two hours at peak	Board will check
	Operation	utilisation.	practically
4.4	Battery Charging time	Should be less than 1 hour	Board will check practically
	of GCS		practically
4.5	Data portability	Ports for data transfer to external	Board will check
		secondary storage devices	practically
4.6	Interface	HDMI, USB, Micro USB, Type C,	Board will check
		10/100/1000 Ethernet.	practically
4.7	Capability	a) Transmit control commands to	Board will check
		UAV.	capability of the system
		b) Receive UAV flight and	practically according the
		propulsion parameters.	mentioned parameters.
		c) Receive, display and record real	
		time day and night video from UAV.	
		d) Capability to control UAV while	
		on the move.	

SN	Parameter	Specifications	Trial directives
4.8	GCS	a) Geographic Map along with UAV	Board will check it
	Application	location, UAV trajectory, camera view	practically and ensure
	Software	polygon, waypoints and flight plan.	that all application is
			working properly.
		b) Real-time video from the UAV with	Board will check it
		on-screen display of important	practically and ensure
		parameters like:-	that all application is
		i. UAV Position (Only in outdoor)	working properly.
		ii. Height of UAV above ground	
		Level (AGL) in outdoor	
		environment.	
		iii. Distance of UAV from GCS	
		iv. Bearing (Azimuth) of UAV from	
		GCS	
		v. Ground speed of UAV	
		vi. UAV Heading/ True North	
		indication	
		vii. Mission time	
		c) Geographic map and real-time video	
		should be displayed at all times during	
		the flight.	
		d) Geographic map and real-time video views window should be resizable	
		and/or switchable to allow user to switch between big map/small video	
		and small map/big video views through	
		a single click/button input.	
		a single chek/button input.	
4.9	Мар	a) Should have the capability to	Board will check
	Formats	integrate geo-referenced raster maps	capability of the system
		provided in at least one of the	practically according the
		commonly used digital map formats	mentioned parameters.
		(GIF, TIFF, DTED and SRTM etc.)	
		As per user requirement.	
		b) Should be able to work with Google	
		Maps, application should have the	
		capability to download maps	
		automatically after specifying location	
		GPS co-ordinates.	

S.N	Parameter	Specifications	Trial directives
	Payload	a)Selection and switch	Board will check capability of
	Controls	on/off of payload	the system practically
		b) Recording on/off	according the mentioned
		c)Switch on/off Night	parameters.
		Recovery Beacon	
4.11	Button	i. Full Camera Control-	Board will check practically.
	based/USB	a). Zoom In/Out	
	Joystick	b). Black/White Hot (only in	
	Controls	case of TI)	
		ii. RPV Mode	
		iii. Altitude Control	
4.12	Video	a) Video should be recorded	Board will check capability of
		in any commonly portable	the system practically
		video formats (AVI/MPEG/	according the mentioned
		MP4 etc)	parameters.
		b) Video of the full flight should be recorded	
		c) Should have capability to	
		take image snapshots at any	
		time during flight	
		d) Software should be	
		provided that will facilitate	
		extraction of imagery from	
		the recorded video post	
		flight	
4.13	Pre-flight	Self-test of UAV system,	Board will check capability of
	checks	Output: go/no go	the system practically
			according the mentioned
			parameters.
5.	Communicatio	n Link:-	1.
5.1	Communication	i) Transmit control	Board will check capability of
	link equipment	commands from GCS to UAV	the system practically
	capability	ii) Transmit parameter of	according the mentioned
		UAV and payload to GCS	parameters
		iii) Transmit day and night	1
		video from UAV to GCS	
5.2	Type of link	Secured digital uplink &	Firm will produce OEM
0.2	1,000111111	downlink with AES	_
			coruncaic.
F 2	Data Lin1	encryption.	Diame
5.3	Data Link	S/C band (2 Ghz to 6 Ghz)	<u> </u>
		with minimum 128 bit AES	certificate.
		encryption.	

SN	Parameter	Specifications	Trial directives
6.	General Syste	m requirements:-	
6.1	Weight (in grams)	The maximum all up	Board will measure weight of UAV birds with the help of weighing machine.
6.2	Assembly/ Disassembly time (In minutes)	≤5 minutes.	Board will check practically.
6.3	Life of Nano UAV	The total technical life of Nano UAV should not be less than 750 flights	Firm will produce OEM certificate.
6.4	IP (Ingress Protection)	IP 53 or better Or As per user requirement.	Firm will submit certificate of Govt. Lab. or NABL or ILAC accredited laboratory
6.5	Environmental Conditions for Operation and Storage	The UAV and associated systems should be certified for operation and storage for following environment conditions. i) Damp Heat: 40°C±2° at RH not less than 90% ii) Operating temperature & Storage temp: -5°C to +50°C, Tolerance ± 10% iii) Ability to withstand dust, drizzle and humid conditions	Firm will submit certificate of Govt. Lab. or NABL or ILAC accredited laboratory.
6.6	Portability and Operation	The Nano UAV should be battery operated portable, light in weight, compact, for day and night surveillance, capable of being carried and operated by two men	Board will check practically. That system is operated by battery and being carried out and operated by two men.
6.7	Battery of AV	The intelligent standard battery pack should have the backup of minimum 20 minutes.	Board will check practically and firm will produce OEM certificate for chemistry of battery.
6.8	Life of AV Battery	Minimum 250 charging cycles.	Firm will produce OEM certificate
6.9	Battery Charger of AV battery	Suitable universal battery charger to charge the batteries up to 98% within two hours.	Board will check practically by charging battery and will ensure that it is capable to charge battery within two hours.

SN	Parameter	Specifications	Trial directives
6.10	Built-in additional power source for the GPS Tracker	The system should include a built-in GPS Tracker equipped with an independent power source, capable of transmitting co-ordinates to the ground control station (GCS) or control station for minimum 72 hours to track/Monitor the lost/crashed UAV	Board will check practically
6.11	Updated list of Mandatory spares/acc essories.	Should be provided (as per user requirement)	BOO will check practically
6.12	Accessories	a) Water proof Back Packs IP66: 1 set b) Field Repair kit: 1 No's c) Battery packs: 3No's d) Spare propeller Sets: 2 No's e) Associated Cables & Mountings: 1 set f) Hard transportation boxes: 1 set g) User, Technical & Maintenance Manual: 1 set h) Log book: 1 set	Board will check physically and firm will submit certificate of Govt. Lab. or NABL accredited or ILAC accredited laboratory for IP66.
7	Additional	Parameters (as per user	
()	requirement	•	DOC 31 1 1
(a)	AI assist flight stabilization.		BOO will check practically.
(b)	Map drawing	g from real time video.	BOO will check practically.

Note:-

- a) All firms are requested to give your response against each parameter required in Figure/Unit where ever mentioned. In those column, vague replies like complied, yes, okay should not be endorsed.
- b) Any other special feature or capability that the firm can provide within above specifications and category may be given at the end of the above proposal.